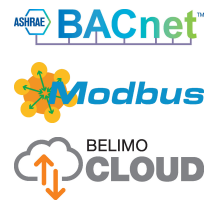**Cloud capable and communicative rotary actuator for ball valves**

• Torque motor 5 Nm
• Nominal voltage AC/DC 24 V
• Control modulating, communicative, hybrid, Cloud
• Conversion of sensor signals
• Ethernet 10/100 Mbit/s, TCP/IP, integrated web server
• Communication via BACnet IP, Modbus TCP and Cloud

BACnet™

Modbus

BELIMO CLOUD

Technical data

Electrical data	Nominal voltage	AC/DC 24 V
	Nominal voltage frequency	50/60 Hz
	Nominal voltage range	AC 19.2...28.8 V / DC 21.6...28.8 V
	Power consumption in operation	3.5 W
	Power consumption in rest position	3 W
	Power consumption for wire sizing	5 VA
	Connection supply / control	Cable 1 m, 6 x 0.5 mm²
	Connection Ethernet	RJ45 socket
	Parallel operation	Yes (note the performance data)
Data bus communication	Communicative control	Cloud BACnet IP Modbus TCP
	Number of nodes	BACnet / Modbus see interface description
Functional data	Torque motor	5 Nm
	Operating range Y	2...10 V
	Input Impedance	34 kΩ
	Operating range Y variable	0.5...10 V
	Position accuracy	±5%
	Manual override	with push-button, can be locked
	Running time motor	90 s / 90°
	Running time motor variable	35...420 s
	Adaptation setting range	manual
	Sound power level, motor	35 dB(A)
	Position indication	Mechanically, pluggable
Safety data	Protection class IEC/EN	III, Safety Extra-Low Voltage (SELV)
	Degree of protection IEC/EN	IP40
	Degree of protection note	IP54 when using protective cap or protective grommet for RJ45 socket
	EMC	CE according to 2014/30/EU
	Mode of operation	Type 1
	Rated impulse voltage supply / control	0.8 kV
	Pollution degree	3
	Ambient temperature	-30...50°C
	Storage temperature	-40...80°C
	Ambient humidity	Max. 95% RH, non-condensing
	Servicing	maintenance-free
Weight	Weight	0.56 kg

Safety notes

⚠

- This device has been designed for use in stationary heating, ventilation and air-conditioning systems and must not be used outside the specified field of application, especially in aircraft or in any other airborne means of transport.
- Outdoor application: only possible in case that no (sea) water, snow, ice, insolation or aggressive gases interfere directly with the device and that it is ensured that the ambient conditions remain within the thresholds according to the data sheet at any time.
- Only authorised specialists may carry out installation. All applicable legal or institutional installation regulations must be complied during installation.
- The device may only be opened at the manufacturer's site. It does not contain any parts that can be replaced or repaired by the user.
- Cables must not be removed from the device.
- To calculate the torque required, the specifications supplied by the damper manufacturers concerning the cross-section, the design, the installation situation and the ventilation conditions must be observed.
- The device contains electrical and electronic components and must not be disposed of as household refuse. All locally valid regulations and requirements must be observed.

Product features

Mode of operation

The actuator is controlled via the Cloud, BACnet IP or Modbus TCP and drives to the position defined by the control signal. Various data points can be written and read via the same interfaces.

Hybrid mode:

The actuator receives its analog control signal from the higher level controller and drives to the position defined. Using the Cloud, BACnet IP or Modbus TCP, various data points can be read and with the exception of the control signal written.

Converter for sensors

Connection option for two sensors (passive sensor, active sensor or switching contact). The actuator serves as an analogue/digital converter for the transmission of the sensor signal to the higher level system.

Communication

The parametrisation can be carried out through the integrated web server (RJ45 connection to the web browser), by communicative means or via the Cloud.

Additional information regarding the integrated web server can be found in the separate documentation.

"Peer to Peer" connection
http://belimo.local:8080
The Notebook must be set to "DHCP".
Make sure that only one network connection is active.
Standard IP address:
http://192.168.0.10:8080
Static IP address
Password (read-only):
User name: «guest»
Password: «guest»
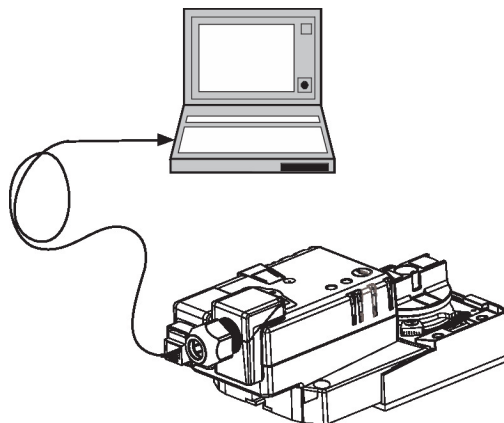
Simple direct mounting

Straightforward direct mounting on the ball valve with only one central screw. The assembly tool is integrated in the plug-in position indication. The mounting orientation in relation to the ball valve can be selected in 90° steps.

Data recording

The recorded data (integrated data recording for 13 months) can be used for analytical purposes.
Download csv files via web browser.

Manual override

Manual override with push-button possible (the gear is disengaged for as long as the button is pressed or remains locked).

Adjustable angle of rotation

Adjustable angle of rotation with mechanical end stops.

High functional reliability	The actuator is overload protected, requires no limit switches and automatically stops when the end stop is reached.
Home position	The first time the supply voltage is switched on, i.e. at the time of commissioning, the actuator carries out an adaptation, which is when the operating range and position feedback adjust themselves to the mechanical setting range.
	The actuator then moves into the position defined by the positioning signal.
Adaptation and synchronisation	An adaptation can be triggered manually by pressing the "Adaptation" button. Both mechanical end stops are detected during the adaptation (entire setting range).
	The actuator then moves into the position defined by the positioning signal.

## Accessories

Electrical accessories	Description	Type
	Grommet for RJ connection module, Multipack 50 pcs.	Z-STRJ.1
Service tools	Description	Type
	Service Tool, with ZIP-USB function, for parametrisable and communicative Belimo actuators, VAV controller and HVAC performance devices	ZTH EU
	Connection cable 5 m, A: RJ11 6/4 ZTH EU, B: 6-pin for connection to service socket	ZK1-GEN

Electrical installation

⚠️ **Supply from isolating transformer.**

Parallel connection of other actuators possible. Observe the performance data.

Wiring diagrams
AC/DC 24 V
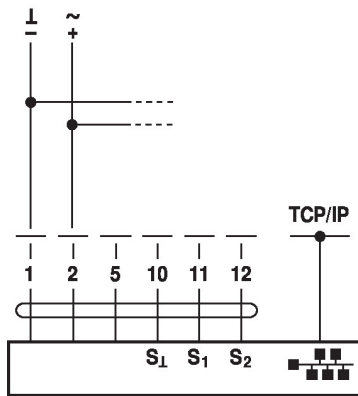
Cable colours:
1 = black
2 = red
5 = orange
10 = yellow-black
11 = yellow-pink
12 = yellow-grey

Connection of a notebook for parametrisation and manual control via RJ45.

Optional connection via RJ45 (direct connection Notebook / connection via Intranet or Internet) for access to the integrated web server

Functions

⚠️ **The connection diagrams shows connections for the first sensor on terminal S1, while the second sensor can be connected identically on terminal S2.**

Parallel use of different sensor types is permitted.

For hybrid operation, S1 is used for the control signal Y and must be configured as an active sensor.

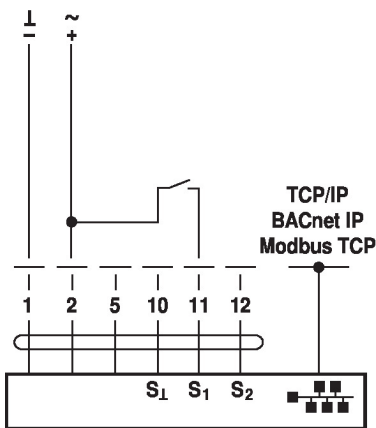## Functions with specific parameters (parametrisation necessary)

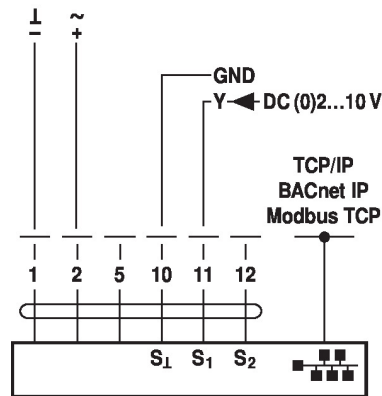TCP/IP (Cloud) / BACnet IP / Modbus TCP

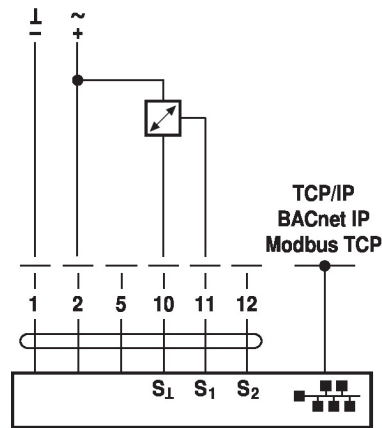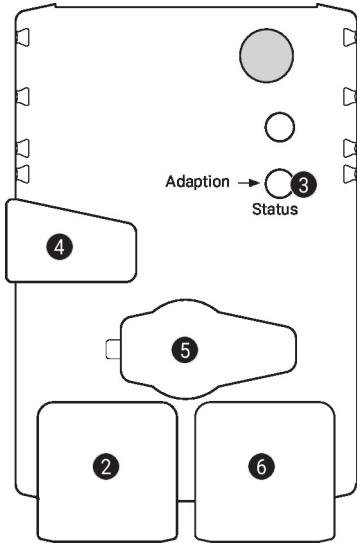TCP/IP (Cloud) / BACnet IP / Modbus TCP with analogue setpoint (hybrid operation)
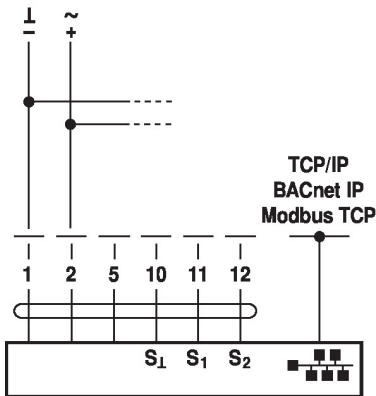
Connection of passive sensors

Connection of active sensors
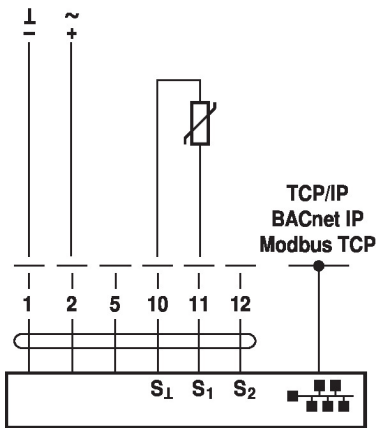
Switching contact connection

Operating controls and indicators

2 **LED display green**

Off:	No power supply or wiring error
On:	Actuator starts operation
Flickering:	In operation

3 **Push-button and LED display yellow**

Off:	Standard mode
On:	Adaptation or synchronisation process active
Press button:	Triggers angle of rotation adaptation, followed by standard mode

4 **Gear disengagement button**

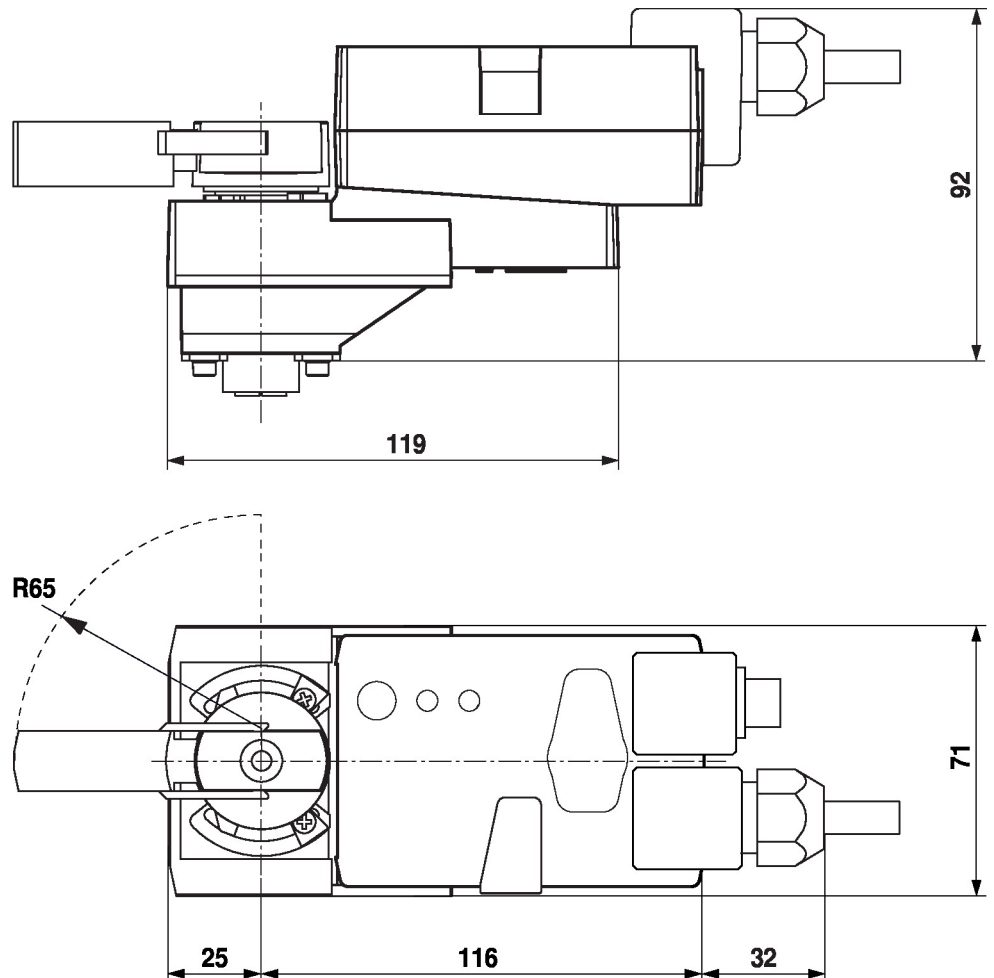|	
Press button:	Gear disengages, motor stops, manual override possible
Release button:	Gear engages, standard mode

5 **Service plug**
For connecting parametrisation and service tools

6 **RJ45 socket**
For the connection of TCP/IP (Cloud), BACnet IP and Modbus TCP

Dimensions

Further documentation

• General notes for project planning
• Instruction Webserver
• Description Protocol Implementation Conformance Statement PICS
• Description Modbus register
• Description clientAPI