

Communicative damper actuator for adjusting dampers in technical building installations

- Air damper size up to approx. 4 m²
- Torque motor 20 Nm
- Nominal voltage AC/DC 24 V
- Control modulating, communicative 2...10 V variable
- Position feedback 2...10 V variable
- Conversion of sensor signals
- Communication via Belimo MP-Bus
- Optimum weather protection for use outdoors (for use in ambient temperatures up to -40°C, there is a separate actuator available with built-in heater)



Technical data

| | | |
|--------------------------|------------------------------------|--|
| Electrical data | Nominal voltage | AC/DC 24 V |
| | Nominal voltage frequency | 50/60 Hz |
| | Nominal voltage range | AC 19.2...28.8 V / DC 21.6...28.8 V |
| | Power consumption in operation | 7 W |
| | Power consumption in rest position | 3.5 W |
| | Power consumption for wire sizing | 9.5 VA |
| | Connection supply / control | Cable 1 m, 4 x 0.75 mm ² (halogen-free) |
| | Parallel operation | Yes (note the performance data) |
| Functional data | Torque motor | 20 Nm |
| | Torque fail-safe | 20 Nm |
| | Communicative control | MP-Bus |
| | Operating range Y | 2...10 V |
| | Input Impedance | 100 kΩ |
| | Operating range Y variable | Start point 0.5...30 V End point 2.5...32 V |
| | Options positioning signal | Open/close 3-point (AC only) Modulating (DC 0...32 V) |
| | Position feedback U | 2...10 V |
| | Position feedback U note | Max. 0.5 mA |
| | Position feedback U variable | Start point 0.5...8 V End point 2.5...10 V |
| | Position accuracy | ±5% |
| | Direction of motion motor | selectable with switch L/R |
| | Direction of motion note | Y = 0 V: At switch position 0 (ccw rotation) / 1 (cw rotation) |
| | Direction of motion variable | electronically reversible |
| | Direction of motion fail-safe | L (ccw) |
| | Manual override | by means of hand crank and locking switch |
| | Angle of rotation | Max. 95° |
| | Angle of rotation note | adjustable starting at 33% in 2.5% steps (with mechanical end stop) |
| | Running time motor | 150 s / 90° |
| | Running time motor variable | 70...220 s |
| Running time fail-safe | <20 s @ -20...50°C / <60 s @ -30°C | |
| Adaptation setting range | manual | |

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| Functional data | Adaptation setting range variable | No action Adaptation when switched on Adaptation after using the hand crank |
| | Override control | MAX (maximum position) = 100% MIN (minimum position) = 0% ZS (intermediate position, AC only) = 50% |
| | Override control variable | MAX = (MIN + 32%)...100% MIN = 0%...(MAX - 32%) ZS = MIN...MAX |
| | Sound power level, motor | 40 dB(A) |
| | Mechanical interface | Universal shaft clamp 12...26.7 mm |
| | Position indication | Mechanically, pluggable |
| | Service life | Min. 60'000 fail-safe positions |
| | Safety data | Protection class IEC/EN |
| Power source UL | | Class 2 Supply |
| Degree of protection IEC/EN | | IP66/67 |
| Degree of protection NEMA/UL | | NEMA 4X |
| Enclosure | | UL Enclosure Type 4X |
| EMC | | CE according to 2014/30/EU |
| Certification IEC/EN | | IEC/EN 60730-1 and IEC/EN 60730-2-14 |
| Certification UL | | cULus according to UL60730-1A, UL60730-2-14 and CAN/CSA E60730-1 The UL marking on the actuator depends on the production site, the device is UL-compliant in any case |
| Mode of operation | | Type 1.AA |
| Rated impulse voltage supply / control | | 0.8 kV |
| Pollution degree | | 4 |
| Ambient temperature | | -30...50°C |
| Ambient temperature note | | -40...50°C for actuator with integrated heating |
| Storage temperature | | -40...80°C |
| Ambient humidity | | Max. 100% RH |
| Servicing | maintenance-free | |
| Weight | Weight | 4.4 kg |

Safety notes



- This device has been designed for use in stationary heating, ventilation and air-conditioning systems and must not be used outside the specified field of application, especially in aircraft or in any other airborne means of transport.
- Only authorised specialists may carry out installation. All applicable legal or institutional installation regulations must be complied during installation.
- Junction boxes must at least correspond with enclosure IP degree of protection!
- The cover of the protective housing may be opened for adjustment and servicing. When it is closed afterwards, the housing must seal tight (see installation instructions).
- The device may only be opened at the manufacturer's site. It does not contain any parts that can be replaced or repaired by the user.
- The cables must not be removed from the device installed in the interior.
- To calculate the torque required, the specifications supplied by the damper manufacturers concerning the cross-section, the design, the installation situation and the ventilation conditions must be observed.
- The device contains electrical and electronic components and must not be disposed of as household refuse. All locally valid regulations and requirements must be observed.
- The actuator is not designed for applications where chemical influences (gases, fluids) are present or for utilisation in corrosive environments in general.
- The actuator may not be used in plenary applications (e.g. suspended ceilings or raised floors).
- The materials used may be subject to external influences (temperature, pressure, construction fastening, effect of chemical substances, etc.), which cannot be simulated in laboratory tests or field trials. In case of doubt, we definitely recommend that you carry out a test. This information does not imply any legal entitlement. Belimo will not be held liable and will provide no warranty.
- Flexible metallic cable conduits or threaded cable conduits of equal value are to be used for UL (NEMA) Type 4X applications.
- When used under high UV loads, e.g. extreme sunlight, the use of flexible metallic or equivalent cable conduits is recommended.

Product features

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| Fields of application | The actuator is particularly suitable for utilisation in outdoor applications and is protected against the following weather conditions: <ul style="list-style-type: none"> - UV radiation - Rain / Snow - Dirt / Dust - Air humidity - Alternating climate / frequent and severe temperature fluctuations (Recommendation: use the actuator with integrated factory-installed heating which can be ordered separately to prevent internal condensation) |
| Mode of operation | Conventional operation: The actuator is connected with a standard modulating signal of 0...10 V and drives to the position defined by the positioning signal. Measuring voltage U serves for the electrical display of the damper position 0.5...100% and as slave control signal for other actuators. Operation on Bus: The actuator receives its digital positioning signal from the higher level controller via the MP-Bus and drives to the position defined. Connection U serves as communication interface and does not supply an analogue measuring voltage. |
| Converter for sensors | Connection option for a sensor (passive or active sensor or switching contact). The MP actuator serves as an analogue/digital converter for the transmission of the sensor signal via MP-Bus to the higher level system. |
| Parametrisable actuators | The factory settings cover the most common applications. Single parameters can be modified with the Belimo Service Tools MFT-P or ZTH EU. |
| Simple direct mounting | Simple direct mounting on the damper shaft with a universal shaft clamp, supplied with an anti-rotation device to prevent the actuator from rotating. |

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| Manual override | By using the hand crank the damper can be actuated manually and engaged with the locking switch at any position. Unlocking is carried out manually or automatically by applying the operating voltage. The housing cover must be removed for manual override. |
| Adjustable angle of rotation | Adjustable angle of rotation with mechanical end stop. The housing cover must be removed to set the angle of rotation. |
| High functional reliability | The actuator is overload protected, requires no limit switches and automatically stops when the end stop is reached. |
| Home position | The first time the supply voltage is switched on, i.e. at the time of commissioning, the actuator carries out a synchronisation. The synchronisation is in the home position (0%). The actuator then moves into the position defined by the positioning signal. |
| Adaptation and synchronisation | An adaptation can be triggered manually by pressing the "Adaptation" button or with the PC-Tool. Both mechanical end stops are detected during the adaptation (entire setting range). Automatic synchronisation after actuating the hand crank is programmed. The synchronisation is in the home position (0%). The actuator then moves into the position defined by the positioning signal. A range of settings can be adapted using the PC-Tool (see MFT-P documentation) |
| Flexible signalling | If a combination with the following electrical accessories is required, please contact your Belimo representative! S2A-F Auxiliary switch 2 x SPDT P200A-F Feedback potentiometer 200 Ω P1000A-F Feedback potentiometer 1 kΩ |

Accessories

| Gateways | Description | Type |
|-------------------------------|---|-------------|
| | Gateway MP zu BACnet MS/TP | UK24BAC |
| | Gateway MP to Modbus RTU | UK24MOD |
| Electrical accessories | Description | Type |
| | Signal converter voltage/current 100 kΩ Supply AC/DC 24 V | Z-UIC |
| | Positioner for wall mounting | SGA24 |
| | Positioner for built-in mounting | SGE24 |
| | Positioner for front-panel mounting | SGF24 |
| | Positioner for wall mounting | CRP24-B1 |
| | MP-Bus power supply for MP actuators | ZN230-24MP |
| Mechanical accessories | Description | Type |
| | Cable gland for cable diameter Ø 4...10 mm | Z-KB-PG11 |
| Service tools | Description | Type |
| | Service Tool, with ZIP-USB function, for parametrisable and communicative Belimo actuators, VAV controller and HVAC performance devices | ZTH EU |
| | Belimo PC-Tool, Software for adjustments and diagnostics | MFT-P |
| | Adapter for Service-Tool ZTH | MFT-C |
| | Connection cable 5 m, A: RJ11 6/4 ZTH EU, B: 6-pin for connection to service socket | ZK1-GEN |
| | Connection cable 5 m, A: RJ11 6/4 ZTH EU, B: free wire end for connection to MP/PP terminal | ZK2-GEN |
| Options ex works only | Description | Type |
| | Heater, with adjustable thermostat | HT24-FG |
| | Heater, with mechanical humidistat | HH24-FG |

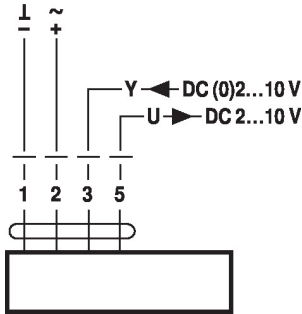
Electrical installation



Supply from isolating transformer.
Parallel connection of other actuators possible. Observe the performance data.

Wiring diagrams

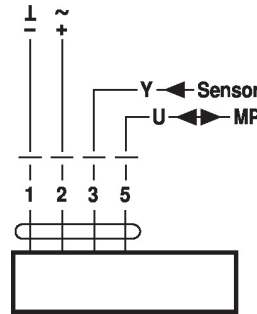
AC/DC 24 V, modulating



Cable colours:

- 1 = black
- 2 = red
- 3 = white
- 5 = orange

Operation on the MP-Bus



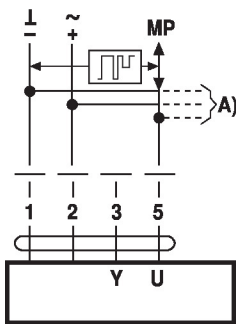
Cable colours:

- 1 = black
- 2 = red
- 3 = white
- 5 = orange

Functions

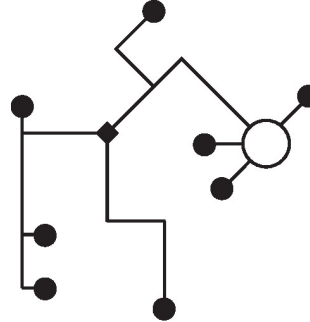
Functions when operated on MP-Bus

Connection on the MP-Bus



A) additional MP-Bus nodes (max. 8)

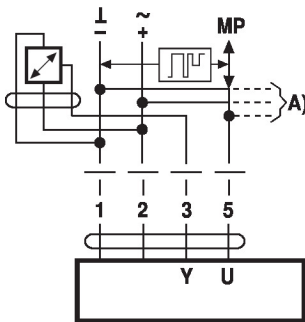
MP-Bus Network topology



There are no restrictions for the network topology (star, ring, tree or mixed forms are permitted).
Supply and communication in one and the same 3-wire cable

- no shielding or twisting necessary
- no terminating resistors required

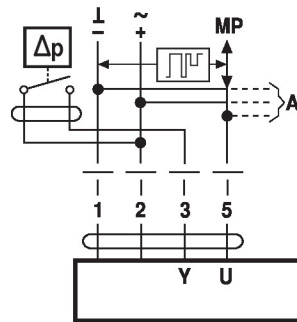
Connection of active sensors



A) additional MP-Bus nodes (max. 8)

- Supply AC/DC 24 V
- Output signal DC 0...10 V (max. DC 0...32 V)
- Resolution 30 mV

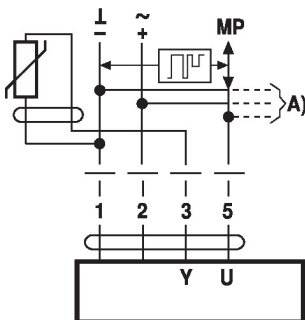
Connection of external switching contact



A) additional MP-Bus nodes (max. 8)

- Switching current 16 mA @ 24 V
- Start point of the operating range must be parametrised on the MP actuator as ≥ 0.5 V

Connection of passive sensors



| | | |
|--------|-----------------------------|-----------------------------------|
| Ni1000 | -28...+98 °C | 850...1600 Ω^2) |
| PT1000 | -35...+155 °C | 850...1600 Ω^2) |
| NTC | -10...+160 °C ¹⁾ | 200 Ω ...60 k Ω^2) |

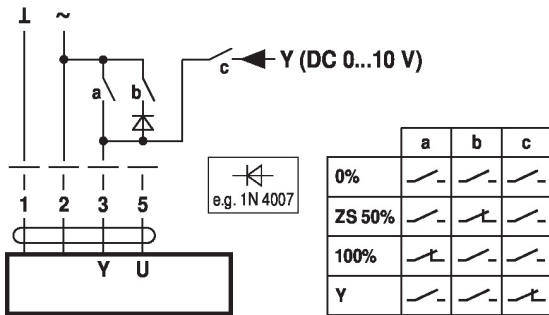
A) additional MP-Bus nodes (max. 8)

- 1) Depending on the type
- 2) Resolution 1 Ohm

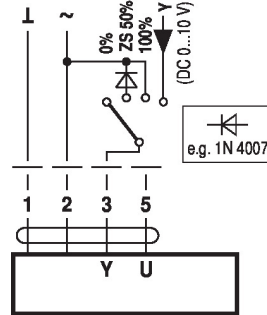
Compensation of the measured value is recommended

Functions with basic values (conventional mode)

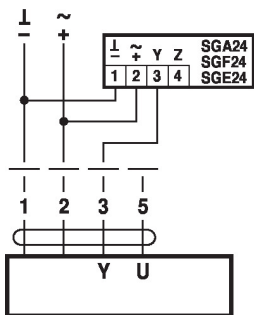
Override control with AC 24 V with relay contacts



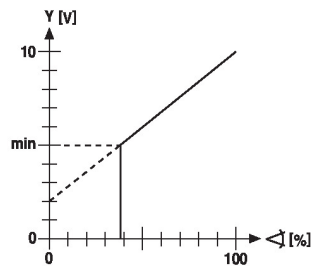
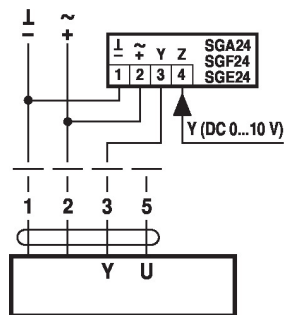
Override control with AC 24 V with rotary switch



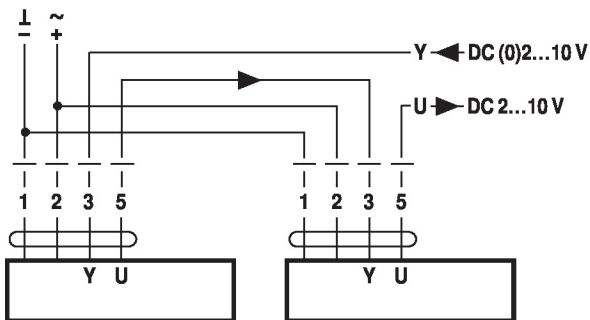
Control remotely 0...100% with positioner SG..



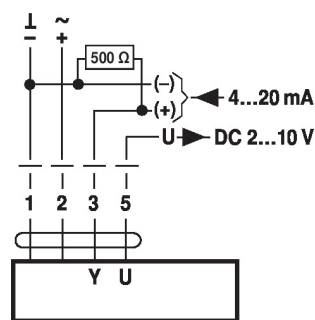
Minimum limit with positioner SG..



Follow-up control (position-dependent)



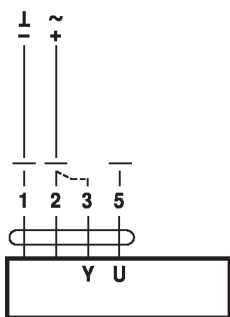
Control with 4...20 mA via external resistor



Caution:

The operating range must be set to DC 2...10 V.
The 500 Ω resistor converts the 4...20 mA current signal to a voltage signal DC 2...10 V

Functional check

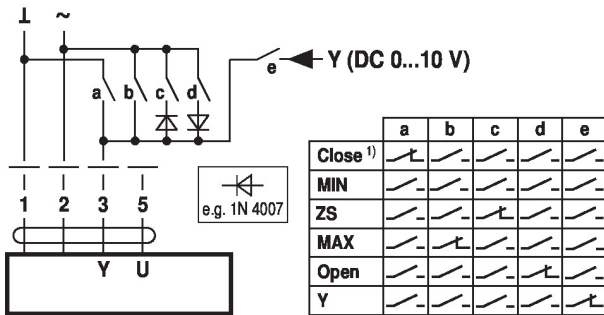


Procedure

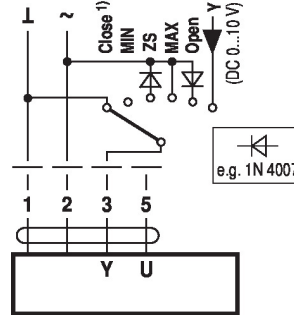
1. Connect 24 V to connections 1 and 2
2. Disconnect connection 3:
 - with direction of rotation 0: Actuator rotates to the left
 - with direction of rotation 1: Actuator rotates to the right
3. Short-circuit connections 2 and 3:
 - Actuator runs in opposite direction

Functions for actuators with specific parameters (Parametrisation necessary)

Override control and limiting with AC 24 V with relay contacts

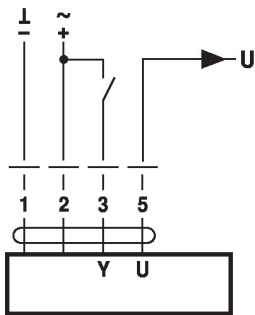


Override control and limiting with AC 24 V with rotary switch

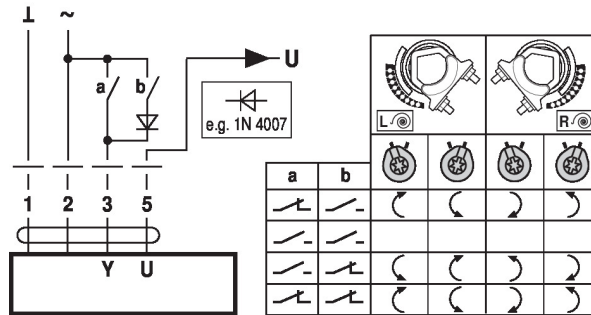


1) **Caution:** This function is only guaranteed if the start point of the operating range is defined as min. 0.5 V.

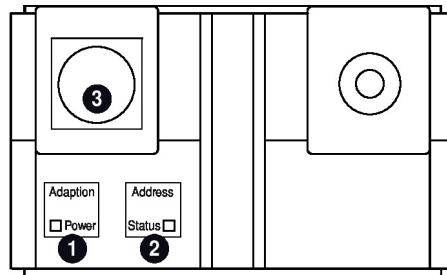
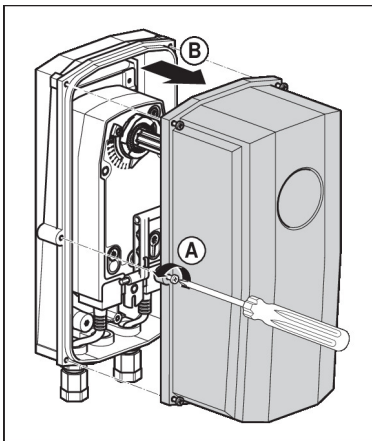
Control open/close



Control 3-point



Operating controls and indicators



- 1 Membrane key and LED display green**
 Off: No power supply or malfunction
 On: In operation
 Press button: Triggers angle of rotation adaptation, followed by standard mode
- 2 Membrane key and LED display gelb**
 Off: Standard mode
 Flickering: MP communication active
 On: Adaptation and synchronising process active
 Flashing: Request for addressing from MP master
 Press button: Confirmation of the addressing
- 3 Service plug**
 For connecting parameterisation and service tools

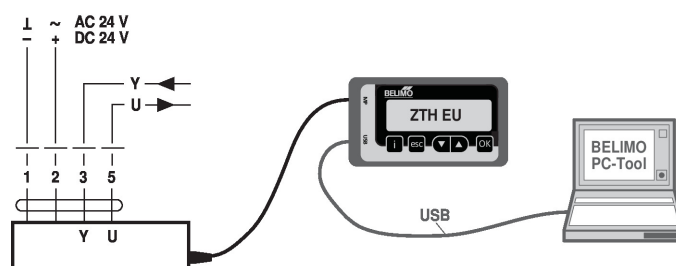
Operating elements

The manual override, locking switch and direction of rotation switch elements are available on both sides

Service

Service tools connection The actuator can be parametrised by ZTH EU via the service socket. For an extended parametrisation the PC tool can be connected.

Connection ZTH EU / PC-Tool



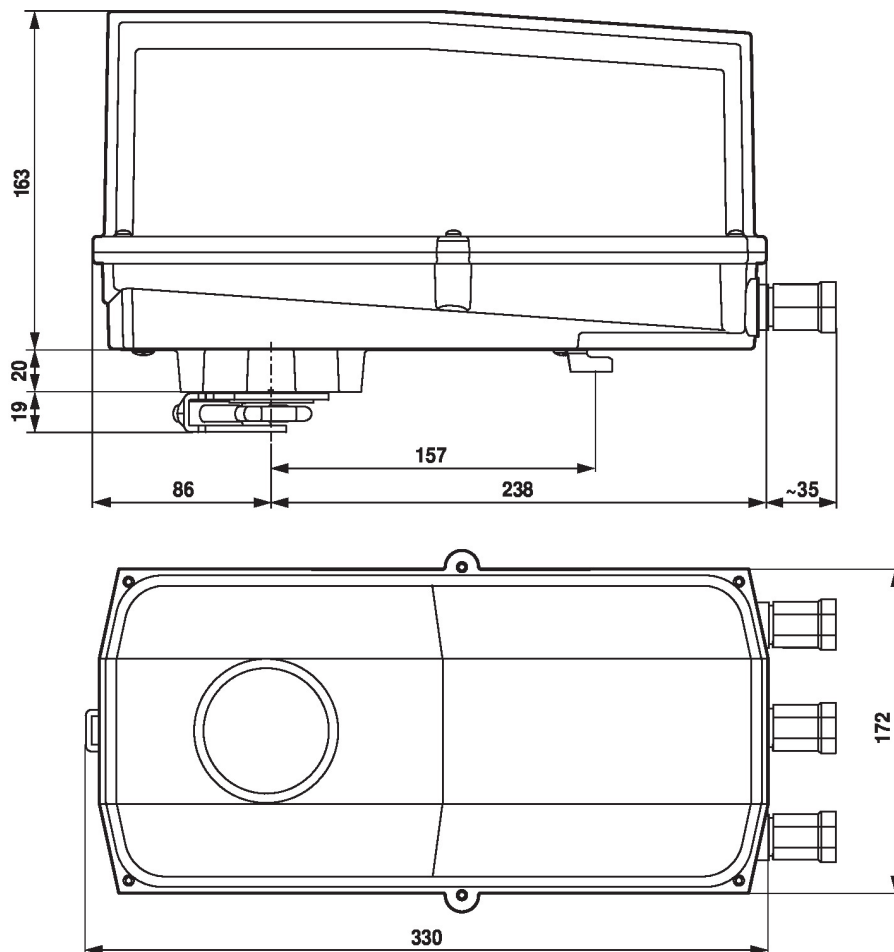
Dimensions

Spindle length

| | |
|--|---|
| | - |
| | 16...105 (Ø12...19) 16...45 (Ø19...26.7) |

Clamping range

| | | |
|--|-----------|---------|
| | | |
| | 12...22 | 12...18 |
| | | |
| | 22...26.7 | 12...18 |



Further documentation

- Overview MP Cooperation Partners
- Tool connections
- Introduction to MP-Bus Technology

Application notes

- For digital control of actuators in VAV applications patent EP 3163399 must be considered.